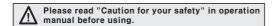
DC Cylindrical Housing Type

Cylindrical (ϕ 18mm) type

■ Features

- •Easy to install cylindrical (\$\phi\$18mm) type
- •Reverse power polarity protection built in
- •Over current protection circuit
- •External sensitivity adjustment (Diffuse reflective type)
- •Able to select the operation mode by control wire (Diffuse reflective type)
- •Protection structure by IP66 (IEC specification)





CE

Specifications

Model	BRP100-DDT	BR100-DDT	BRP400-DDT	BR400-DDT	BR20M-TDTD	BR20M-TDTL	
	BRP100-DDT-P	BR100-DDT-P	BRP400-DDT-P	BR400-DDT-P	BR20M-TDTD-P	BR20M-TDTL-P	
Туре		Diffuse	Throug	h-beam			
Detecting distance	(*1)100mm (*1)400mm			20m			
Detecting target	Transparent, Translucent, Opaque materials			Opaque materials of Min. ø 15mm			
Response time	Max. 1ms				Max. 3ms		
Power supply	12-24VDC ±10% (RippleP-P:Max. 10%)						
Current consumption	Max. 40mA						
Light source	Infrared LED (modulated)						
Sensitivity adjustment	Adjustable VR				Fixed		
Operation mode	Selectable Light ON or Dark ON by control wire				Dark ON	Light ON	
Control output	NPN open collector output Dad voltage: Max. 30VDC, Load current: Max. 200mA, Residual voltage: Max. 1VDC						
	PNP open collector output © Output voltage:Min. power voltage-2.5V, Load current:Max. 200mA						
Protection circuit	Short-circuit protection, Reverse polarity protection						
Indication	Operation indicator : Red LED				Power indicator (Emitter): Red LED, Operation indicator (Receiver): Red LED		
Connection	Outgoing cable						
Insulation resistance	Min. 20MΩ (at 500VDC)						
Noise strength	±240V the square wave noise (pulse width:1μs) by the noise simulator [
Dielectric strength	500VAC 50/60Hz for 1 minute						
Vibration	1.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 2 hours						
Shock	500m/s ² (50G) in X, Y, Z directions for 3 times						
Ambient illumination	Sunlight: Max. 11,000/x, Incandescent lamp: Max. 3,000/x						
Storage temperature	-10 ~ +60 °C (at non-freezing status) Storage : -25 ~ +70 °C						
Ambient humidity	35 ~ 85%RH, Storage : 35 ~ 85%RH						
Protection	IP66 (IEC specification)						
Material	Case:Plastic (Black), Lens:PC	Case:C3604BD (Cr-plate), Lens:PC	Case:Plastic (Black), Lens:PC	Case:C3604BD (Cr-plate), Lens:PC	Case:C3604I Lens:PC	BD(Cr-plate),	
Cable						nm, Length:2m 5mm, Length:2m	
Accessory	Mounting Nuts	uting Nuts Mounting Nuts, Washer					
Approval	(€						
Weight□	Approx. 100g	Approx. 120g	Approx. 100g	Approx. 120g	Appro	x. 300g	

(₩1) It for Non-glossy whire paper(100×100mm).

(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

(G) Display unit

(H) Sensor controller

(I) Proximity sensor

(J) Photo electric sensor

(K) Pressure sensor

(L) Rotary encoder

(M) 5-Phase stepping motor & Driver & Controller

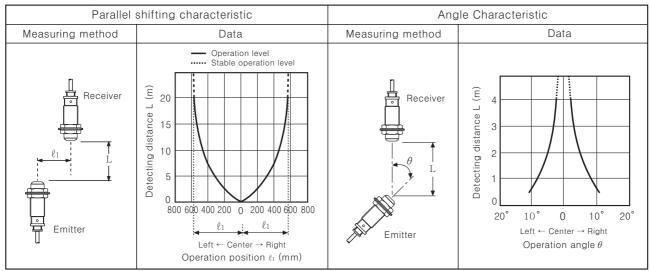
Autonics J-42

BR Series

■ Characteristic

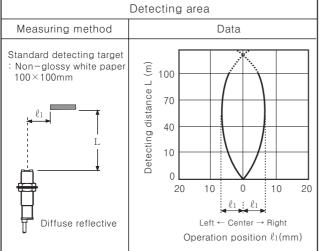
OThrough-beam

●BR20M-TDT, BR20M-TDT-P

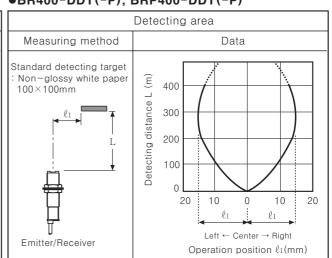


ODiffuse reflective

●BR100-DDT(-P), BRP100-DDT(-P)

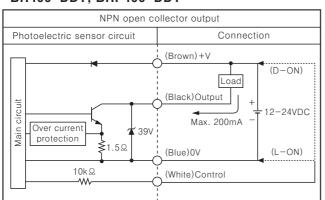


●BR400-DDT(-P), BRP400-DDT(-P)

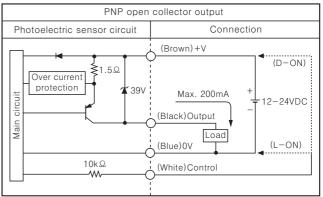


Control output circuit diagram

BR100-DDT, BRP100-DDT, BR400-DDT, BRP400-DDT



•BR100-DDT-P, BRP100-DDT-P, BR400-DDT-P, BRP400-DDT-P



**Selectable Light ON / Dark ON mode by control wire Light ON: Connect control wire to 0V Dark ON: Connect control wire to +V

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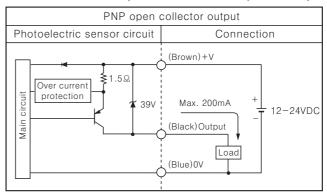
DC Cylindrical Housing Type

■Control output diagram

BR20M-TDTD2/BR20M-TDTL2(Receiver)

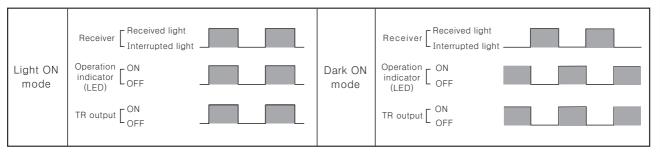
NPN open collector output Photoelectric sensor circuit Connection (Brown) +V Load (Black) Output Max. 200mA + 12-24VDC (Blue) 0V (Blue) 0V

•BR20M-TDTD2-P/BR20M-TDTL2-P(Receiver)



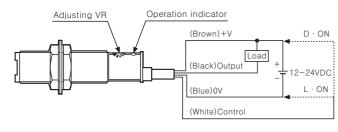
*Dark ON mode is standard mode for BR4M.(Light ON mode: Option)

Operation mode

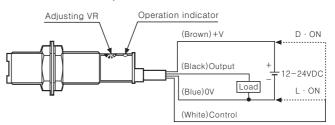


Connections

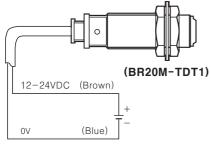
•BR100-DDT, BRP100-DDT, BR400-DDT, BRP400-DDT



●BR100-DDT-P, BRP100-DDT-P, BR400-DDT-P. BRP400-DDT-P

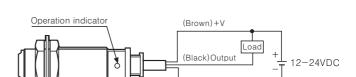


●BR20M-TDT(L) / BR20M-TDTD(L)-P



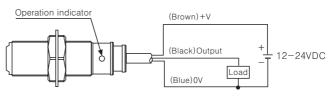
** Since 2001/Oct., inner circuit has been changed therefore do not use previous products(Before 2001/Oct.) together. When need to replace this, it must be one set.

Before Oct./2001 After	After Oct./2001	Condition	
Emitter	Receiver	Disable compatible	
Receiver	Emitter	Enable compatible	



(Blue)0V

(BR20M-TDTD2 / BR20M-TDTL2)



(BR20M-TDTD2-P / BR20M-TDTL2-P)

(A) Counter

(B) Timer

(C) Temp.

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

(G) Display unit

(H) Sensor controller

(I) Proximity sensor

(J) Photo electric sensor

(K) Pressure sensor

(L) Rotary encoder

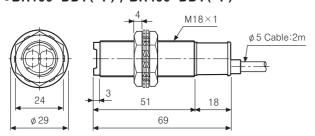
(M) 5-Phase stepping motor & Driver & Controller

Autonics J-44

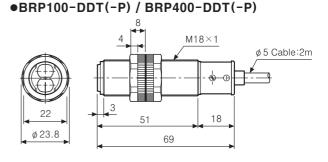
BR Series

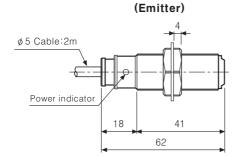
Dimensions

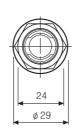
●BR100-DDT(-P) / BR400-DDT(-P)

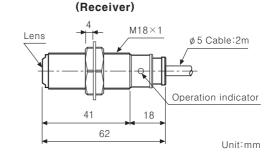


●BR20M-TDTD(L) / BR20M-TDTD(L)-P







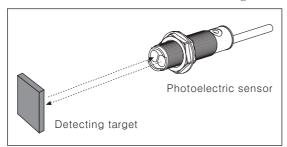


Installation and sensitivity adjustment

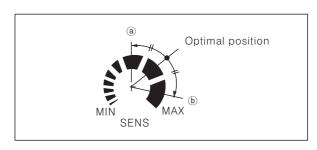
Please supply the power to the sensor after installing the emitter and the receiver in face to face, and then adjust an optical axis and the sensitivity as follow;

ODiffuse Reflective type

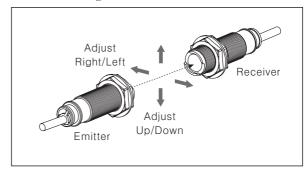
1. Even though the diffuse reflective type is set at max. sensitive position, the sensitivity of the sensor must be adjusted in accordance with the existence of the reflective material in background.



- 2. Set the target at a position to be detected by the beam, then turn the adjuster down to point ⓐ where the indicator just turns on from Min. position of the adjuster.
- 3. Take the target out of the sensing area, then turn the adjuster until point (b) where the indicator turns on. If the indicator does not turn on, max. position is point (b).
- 4. Set the adjuster at the center of two switching point ⓐ, ⓑ.
- *The detecting distance indicated in the specification chart is that of non-glossy white paper in the target size 50×50mm.



- 1. Supply the power to the photoelectric sensor, after installing the emitter and the receiver in face to face.
- 2. Set the receiver in center of position where indicator turns on, as adjusting the receiver and the emitter right and left, up and down.
- 3. Fix both units tightly after checking that the units detect the target.



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